

Live Heap Space Analysis for Languages with Garbage Collection

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 - ▶ **memory allocated**
 - ▶ number calls to certain methods: billable events on a mobile

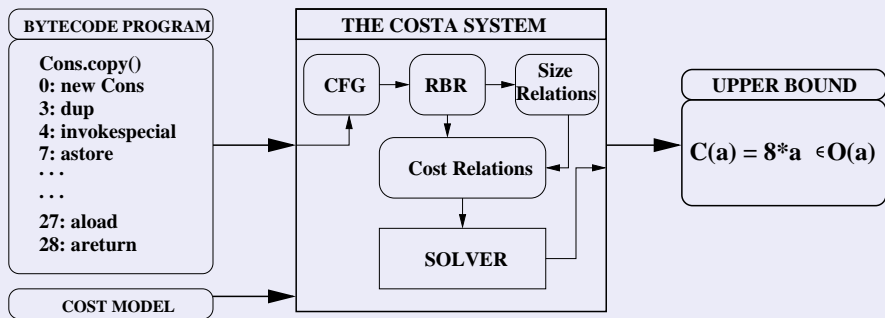
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- Finding the exact cost of programs is *undecidable*, but it is possible to infer useful information (*bounds*):
 - ▶ **Upper bounds**: a program runs within the resources available.
 - ▶ *Lower bounds*: useful for scheduling distributed execution.

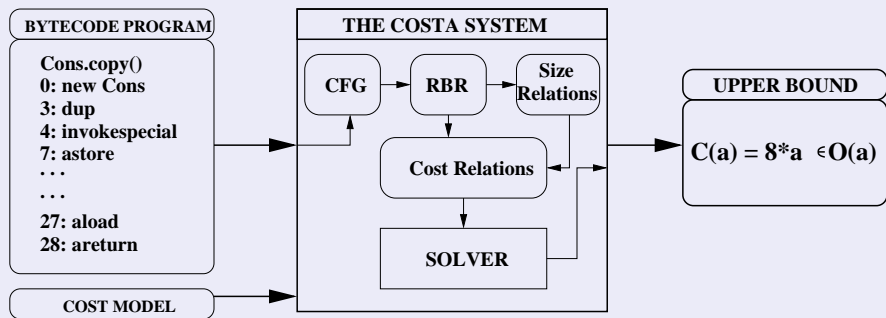
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 - ▶ **Upper bounds**: a program runs within the resources available.
 - ▶ *Lower bounds*: useful for scheduling distributed execution.
- Two classes of upper bounds can be considered:
 - ▶ **non-asymptotic** (or concrete, or micro-analysis)
 - ▶ asymptotic (or macro-analysis)

COSTA: Cost Analyzer for Java Bytecode

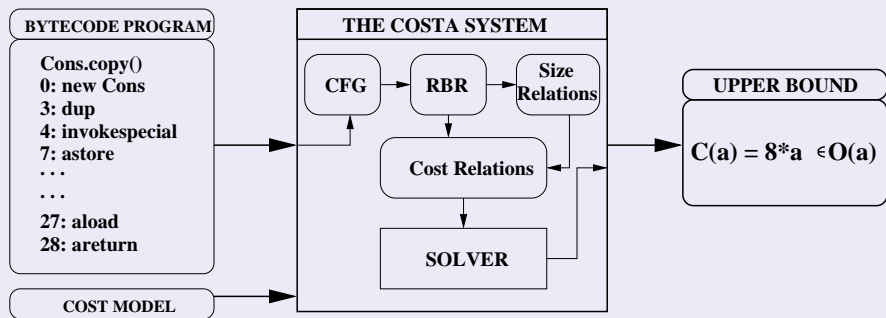


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I will focus on the main components and on cost models *heap* and *peak*.

HEAP: Total Allocation Analysis

- Symbolic *cost model* for heap consumption, $size(\text{Tree})$, $size(\text{Integer})$..
- We get upper bounds of the *total* allocated memory.
- In presence of **garbage collection (GC)**, it is a too pessimistic estimation of the actual memory consumption.

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PEAK: Live Heap Space Analysis

- Aims at approximating the maximum or **peak** heap usage.
- Scope-based GC model:
 - 1 Reclaims unreachable memory when methods return. This assumption can be refined up to an ideal GC.
 - 2 Collects unreachable objects which have been created during the execution of the corresponding method call and not before.
- Much tighter estimation in presence of GC.

From Java to Intermediate representation

```
class Test {  
    static Tree m(int n) {  
        if ( n>0 ) return  
            new Tree(m(n-1),m(n-1),f(n));  
        else return null;  
    }  
  
    static int f(int n) {  
        int a=0,i=n;  
        for (; n>1 ; n=n/2 )  
            a += g(n).intValue();  
        for(; i>1; i=i/2)  
            a *= h(i).intValue();  
        return a;  
    }  
  
    static Integer g(int n) {  
        Integer x=new Integer(n);  
        return new Integer(x.intValue()+1);  
    }  
    static Long h(int n) {  
        return new Long(n-1);  
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$$\begin{aligned}
 m(\langle n \rangle, \langle r \rangle) ::= & \\
 & \mathbf{n} > \mathbf{0}, \\
 & s_0 := \text{new Tree}^1; \\
 & s_1 := n - 1, \\
 & m(\langle s_1 \rangle, \langle s_1 \rangle), \\
 & s_2 := n - 1, \\
 & m(\langle s_2 \rangle, \langle s_2 \rangle), \\
 & f(\langle n \rangle, \langle s_3 \rangle), \\
 & \text{init}(\langle \langle s_0, s_1, s_2, s_3 \rangle, \langle \rangle \rangle), \\
 & r = s_0. \\
 \\
 m(\langle n \rangle, \langle r \rangle) ::= & \\
 & \mathbf{n} \leq \mathbf{0}, \\
 & r := \text{null}.
 \end{aligned}$$

$$\begin{aligned}
 f(\langle n \rangle, \langle r \rangle) ::= & \\
 & a := 0, \\
 & i := n, \\
 & f_c(\langle n, a \rangle, \langle n, a \rangle), \\
 & f_d(\langle i, a \rangle, \langle i, a \rangle), \\
 & r := a. \\
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 f_c(\langle n, a \rangle, \langle n, a \rangle) ::= & \\
 & \mathbf{n} > \mathbf{1}, \\
 & g(\langle n \rangle, \langle s_0 \rangle), \\
 & \text{intValue}_1(\langle s_0 \rangle, \langle s_0 \rangle) \\
 & a := a + s_0, \\
 & n := n/2, \\
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m(⟨n⟩, ⟨r⟩)::=
    n > 0,
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    init(⟨s0, s1, s2, s3⟩, ⟨⟩),
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m(⟨n⟩, ⟨r⟩)::=
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From Intermediate representation to cost equations

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m( $\langle n \rangle$ ,  $\langle r \rangle$ ) ::=
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  init( $\langle s_0, s_1, s_2, s_3 \rangle$ ,  $\langle \rangle$ ),
  r = s0.

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```

m( $\langle n \rangle$ ,  $\langle r \rangle$ ) ::=
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```

```

m(n) = size(Tree1) +           {n > 0}
      m(n-1) + m(n-1) + f(n) +
      init(1, n-1, n-1, s3)
m(n) = 0                          {n ≤ 0}

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$$\begin{aligned}
 m(\langle n \rangle, \langle r \rangle) ::= & \\
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 m(n) = & \text{size}(\text{Tree}^1) + && \{n > 0\} \\
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 m(n) = & 0 && \{n \leq 0\}
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$$m(n) = 0 \{n \leq 0\}$$

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  s0 := new Tree1;
  s1 := n - 1,
  m( $\langle s_1 \rangle$ ,  $\langle s_1 \rangle$ ),
  s2 := n - 1,
  m( $\langle s_2 \rangle$ ,  $\langle s_2 \rangle$ ),
  f( $\langle n \rangle$ ,  $\langle s_3 \rangle$ ),
  init( $\langle s_0, s_1, s_2, s_3 \rangle$ ,  $\langle \rangle$ ),
  r = s0.

```

```

m( $\langle n \rangle$ ,  $\langle r \rangle$ ) ::=
  n ≤ 0,
  r := null.

```

```

m(n) = size(Tree1) + {n > 0}
      m(n-1) + m(n-1) + f(n) +
      init(1, n-1, n-1, s3)

```

```

m(n) = 0 {n ≤ 0}

```

```

f(n) = fc(n, 0) + fd(n, a') {}

```

```

fc(n, a) = g(n) + fc(n/2, a') {n > 1}

```

```

fc(n, a) = 0 {n ≤ 1}

```

```

fd(i, a) = h(i) + fd(i/2, a') {i > 1}

```

```

fd(i, a) = 0 {i ≤ 0}

```

```

g(n) = size(Integer2) + size(Integer3) {}

```

```

h(n) = size(Long4) {}

```

```

init(this, l, r, d) = 0 {}

```


From Cost Relations to Upper Bounds

solutions computed for f

$$total(f) = total(f_c) + total(f_d)$$

```
for (; n>1 ; n=n/2 ) a += g(n).intValue();
```

```
for (; i>1 ; i=i/2 ) a *= h(i).intValue();
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$$f_c(n) = \log(n) * (\text{size}(\text{Integer}^3) + \text{size}(\text{Integer}^2))$$

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solutions computed for m

$$m(n) = 2^n * \underbrace{(total(f) + \text{size}(\text{Tree}^1))}_{\text{exp times}}$$

```
new Tree(m(n-1), m(n-1), f(n));
```

Why Live Heap Space Analysis is Different?

Basic idea in total allocation:

$$\mathbf{total}(\{\mathbf{m}_1; \mathbf{m}_2\}) = \mathbf{total}(\mathbf{m}_1) + \mathbf{total}(\mathbf{m}_2)$$

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$$\mathbf{peak}(\{\mathbf{m}_1; \mathbf{m}_2\}) = \mathbf{max}(\mathbf{peak}(\mathbf{m}_1), \mathbf{escaped}(\mathbf{m}_1) + \mathbf{peak}(\mathbf{m}_2))$$

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- 1 STEP 1: **Escaped memory analysis**
- 2 STEP 2: Peak consumption cost relations

Example

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class Test {
    static Tree m(int n) {
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    static int f(int n) {
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■ g peak



1

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 g peak
 g escaped



1 2

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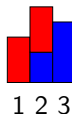
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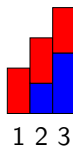
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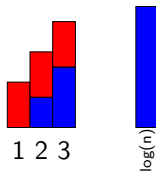
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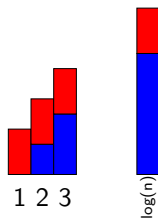
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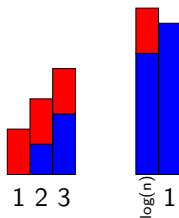
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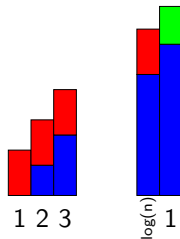
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■ g peak
■ g escaped
■ h peak



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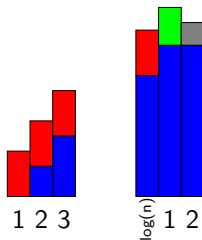
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■ g peak
■ g escaped
■ h peak
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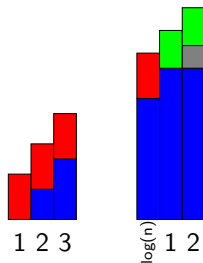
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■ g peak
■ g escaped
■ h peak
■ h escaped



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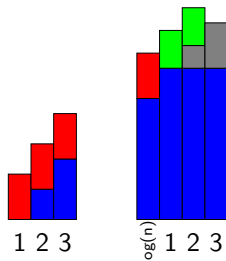
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■ g escaped
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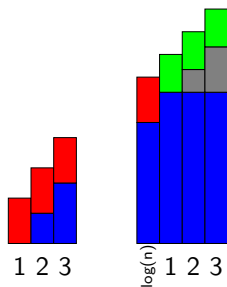
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■ g peak
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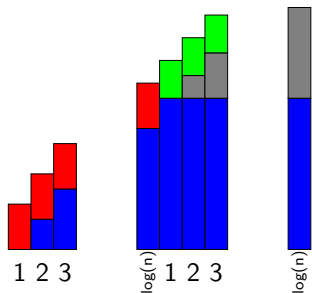
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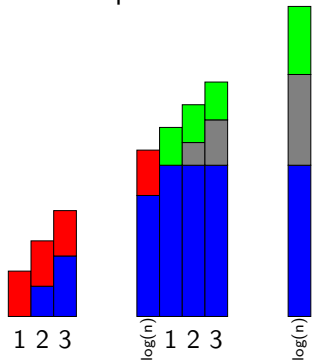
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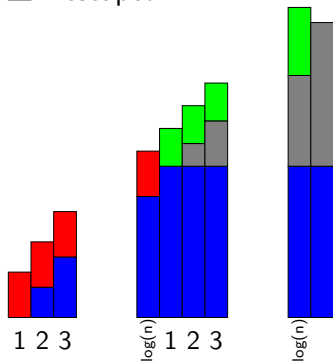
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■ g peak
■ g escaped
■ h peak
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Step 1: Inference of Escaped Memory Bounds

- Infer upper bounds on the total memory consumption
- Remove from the bounds the **collectable** objects
- The set of collectable objects can be approximated from the information computed by **escape** analysis

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collectable objects from m

the objects that have been created along the execution of m and will not be in the memory upon exit from m

Collectable Objects

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$$\text{collectable}(g) = \{\text{Integer}^2\}$$

$$\text{collectable}(h) = \emptyset$$

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      Tree(m(n-1),m(n-1),f(n));
    else return null;
  }

  static int f(int n) {
    int a=0,i=n;
    for(; n>1;n=n/2 )
      a += g(n).intValue();
    for(; i>1; i=i/2)
      a *= h(i).intValue();
    return a;
  }

  static Integer g(int n) {
    Integer x=new Integer2(n);
    return new Integer3(x.intValue()+1);
  }

  static Long h(int n) {
    return new Long4(n-1);
  }
} // end of class Test

```

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Bounds on Escaped Memory

escaped memory of a procedure p

- given the set of collectable objects after return from p , $collectable(p)$,
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Step 2: Inference of Live Memory Bounds

- Build cost relations which capture the basic idea

$$\mathbf{peak}(\{m_1; m_2\}) = \mathbf{max}(\mathbf{peak}(m_1), \mathbf{escaped}(m_1) + \mathbf{peak}(m_2))$$

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peak cost relation

$\mathcal{T}(b_1, \dots, b_n) ::=$

- ▶ if b_1 is a call, then $\mathit{max}(\mathit{peak}(b_1), \mathit{escaped}(b_1) + \mathcal{T}(b_2, \dots, b_n))$
- ▶ if b_1 is an instruction, then $\mathit{total}(b_1) + \mathcal{T}(b_2, \dots, b_n)$

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- For the following code in m:

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new Tree(m(n-1), m(n-1), f(n));
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- An upper bound of the equations:

$$peak_m(n) = 2^n * size(Tree^1) + peak_f(n)$$

Live Heap Bounds vs. Total Memory Bounds

solutions computed from peak cost relation

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tighter bound for f

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Conclusions

- We have presented an automatic live heap space analysis for garbage-collected languages.
- It generates at compile-time **cost relations** which define the peak consumption of a program as a function of its input data size.
- The CRs obtained can be solved with standard UBs solvers (PUBS).
- We have successfully analyzed the JOlden benchmark suite.
- Applications: verification, certification (embedded systems, critical/real-time apps), program optimization and understanding, etc.

Future Work

- Adapt our techniques to region-based garbage collection
- The idea could be used to estimate other non-accumulative resources.

Info on Costa:

<http://costa.ls.fi.upm.es>