

Decomposing Global Constraints into SAT

Christian Bessiere, George Katsirelos, Nina Naroditskaya,
Claude-Guy Quimper, **Toby Walsh**

***Decomposing Global
Constraints into SAT***
***(alias: why we need constraint
programming!)***

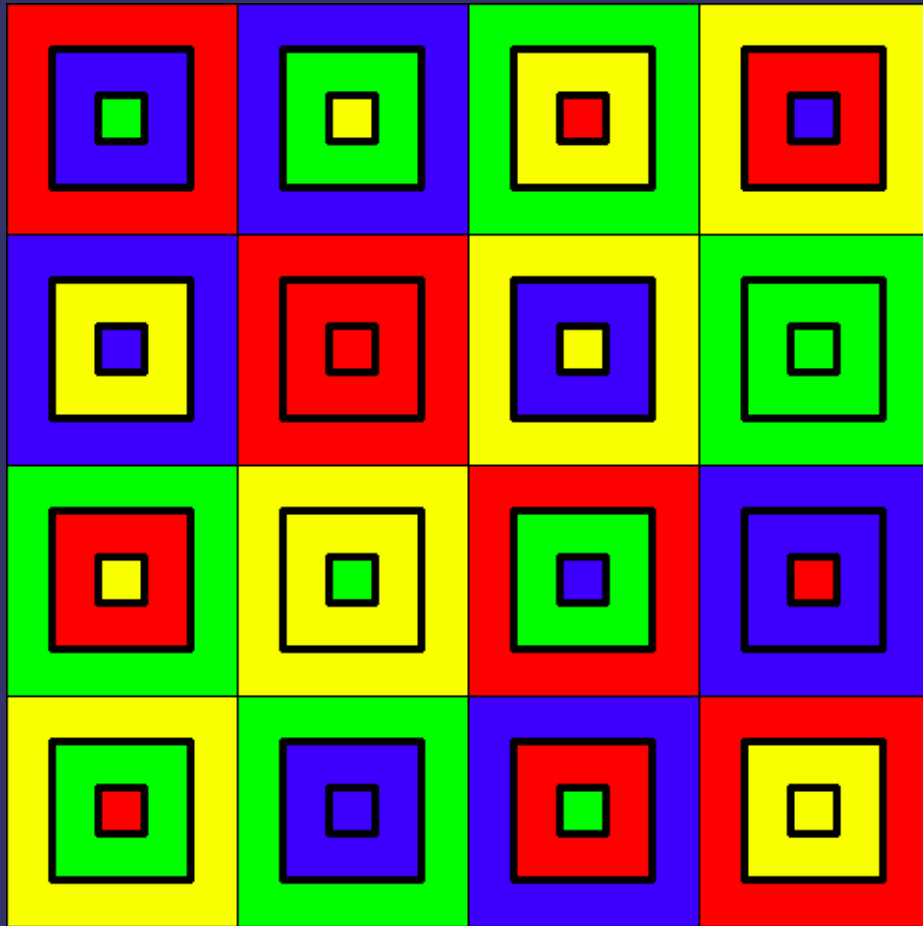
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Motivation

- ⇒ Mature and effective technologies in constraint programming
 - Global constraints
 - Search methods
 - Branching heuristics
 - ...

- ⇒ Many successful applications
 - Scheduling, configuration, ...

Global constraints



- Capture common patterns
 - E.g. permutation = AllDifferent
 - Associated propagator
 - Efficient inference methods

Motivation

- Many global constraints can be effectively decomposed
 - REGULAR constraint in a call centre rostering problem [Quimper & Walsh CP06]
 - REGULAR, SEQUENCE, TABLE constraints [Bacchus CP06]
 - GRAMMAR constraint [Quimper & Walsh CP07]
 - ALL DIFFERENT constraint [Bessiere et al IJCAI 09]



Why not just decompose all global constraints?

- MIP decomposes everything into linear inequalities after all
- Many free advantages
 - nogood learning, incremental propagators, impact based heuristics, ...

*What can you do in SAT and what can
you only do in CP?*

Decomposing GLOBALs

- Successful examples
 - REGULAR
 - SEQUENCE
 - CFG
 - ALL DIFFERENT
 - NVALUES
 - GCC
 - ...

Decomposing GLOBALs

- Successful examples
 - **REGULAR**
 - SEQUENCE
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 - **ALL DIFFERENT**
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 - ...

Main results

- ⇒ Some surprisingly complex propagation algorithms for global constraints can be efficiently decomposed
- ⇒ However, there exist other propagation algorithms which have an exponential size decomposition



REGULAR constraint

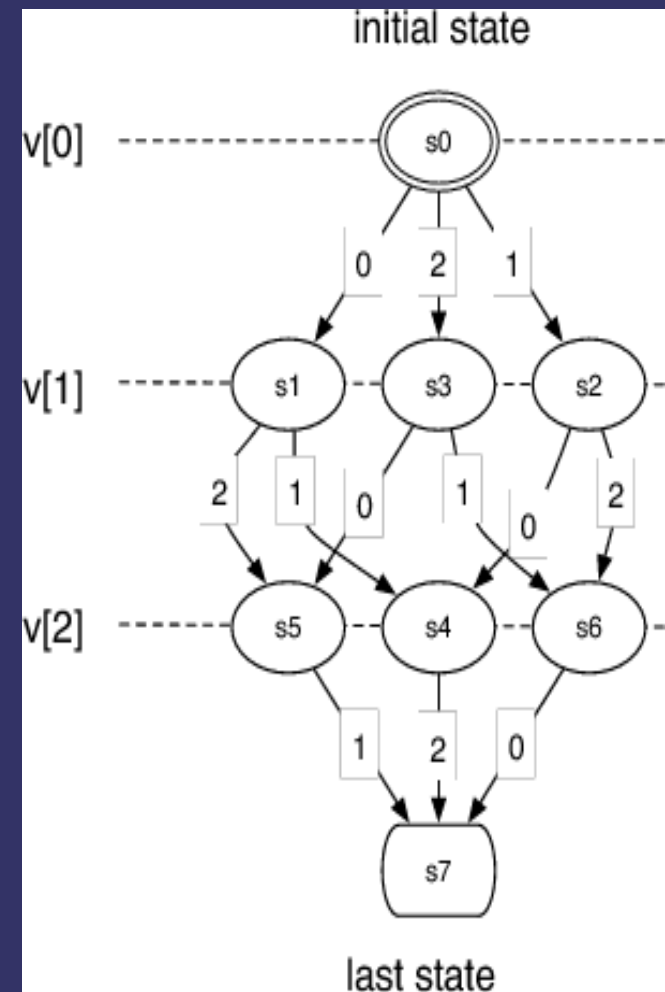
- Sequence of vars defines a regular language
- Useful in rostering and many other problems

Shift = Days | Nights | Days Shift | Nights Shift

- Days = d | d Days
- Nights = n | n n | n n n

REGULAR constraint

- Sequence of vars defines a regular language
- Complex propagator based on dynamic programming
 - Enforces domain consistency in $O(ndQ)$



REGULAR constraint

- Simple decomposition
 - Does not hinder propagation
 - Again in $O(ndQ)$ time and space
- Introduce sequence of vars for state of automaton after j th step
 - Then simply post transition constraints
 - $Q_{i+1} = t(Q_i, X_i)$

REGULAR constraint

- Rostering example

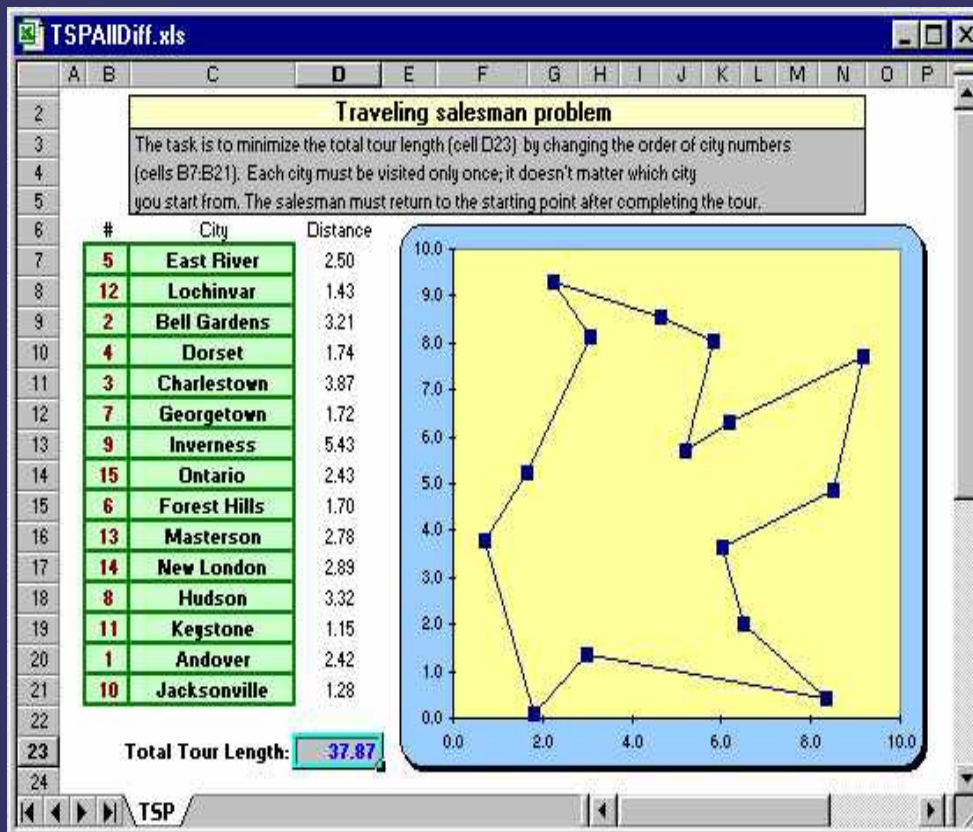
Shift = Days | Nights | Days Shift | Nights
Shift

- Days = 0 | 0 Days
- Nights = 1 | 1 1 | 1 1 1

- Transition constraints

- $Q_{i+1} = X_i * (Q_i + X_i)$
- Q_i in $[0,3]$

AllDifferent constraint



- One of the oldest global constraints
 - Appeared in ALICE [Laurier 78]
- One of the most useful global constraints
 - Timetabling
 - Scheduling
 - Routing
 - ...

AllDifferent constraint

→ AllDifferent(X_1, \dots, X_n) iff
 $X_i \neq X_j$ for $i < j$

E.g AllDifferent(1,2,4) but not
AllDifferent(1,2,1)

AllDifferent constraint

- ⇒ Decompose into $O(n^2)$ inequalities
 - This hinders propagation
 - $X1, X2, X3 \in \{1,2\}$
 - $X1 \neq X2, X1 \neq X3, X2 \neq X3$ are domain consistent
 - However, $AllDifferent(X1,X2,X3)$ has no solution

Can we decompose whilst maintaining a global view?

AllDifferent constraint

- ⇒ Range/bound consistency propagator can be encoded into SAT
 - Based on Hall intervals
- ⇒ Domain consistency propagator requires exponential size SAT encoding
 - Based on circuit complexity

AllDifferent constraint

⇒ Bound consistency

- Max and min in each domain have bound support
- Bound support = satisfying assignment in which each var is bet max and min

⇒ Range consistency

- Every value in each domain has bound support

⇒ Domain consistency

- Every value in each domain has support
- Support = satisfying assignment in which each var is assigned value from its domain

AllDifferent constraint

- ⇒ Bound and range consistency
 - Central concept is **Hall interval**
 - Hall interval = interval of m values which contains domains of m variables
 - Other variables must find their bound supports outside of this!

AllDifferent constraint

	1	2	3	4	5
X1			*	*	
X2	*	*	*	*	
X3			*	*	
X4		*	*	*	*
X5	*				

AllDifferent constraint

	1	2	3	4	5
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X2	*	*	*	*	
X3			*	*	
X4		*	*	*	*
X5	*				

[1,1] is a Hall interval

AllDifferent constraint

	1	2	3	4	5
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X2	*	*	*	*	
X3			*	*	
X4		*	*	*	*
X5	*				

[1,1] is a Hall interval, X5 consumes interval

AllDifferent constraint

	1	2	3	4	5
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X2	*	*	*	*	
X3			*	*	
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[1,1] is a Hall interval, $X2 \neq 1$

AllDifferent constraint

	1	2	3	4	5
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X2		*	*	*	
X3			*	*	
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X5	*				

[1,1] is a Hall interval, $X2 \neq 1$

AllDifferent constraint

	1	2	3	4	5
X1			*	*	
X2		*	*	*	
X3			*	*	
X4		*	*	*	*
X5	*				

[3,4] is a Hall interval, contains X1 and X3

AllDifferent constraint

	1	2	3	4	5
X1			*	*	
X2		*	*	*	
X3			*	*	
X4		*	*	*	*
X5	*				

$[3,4]$ is a Hall interval, $X2 \cap [3,4] = 0$, $X4 \cap [3,4] = 0$

AllDifferent constraint

	1	2	3	4	5
X1			*	*	
X2		*			
X3			*	*	
X4		*			*
X5	*				

$[3,4]$ is a Hall interval, $X2 \cap [3,4] = 0$, $X4 \cap [3,4] = 0$

AllDifferent constraint

⇒ Simple decomposition

- $A_{ilu}=1$ iff $X_i \in [l,u]$
- $\sum A_{ilu} \leq u-l+1$

AllDifferent constraint

⇒ Simple decomposition

- $A_{ilu}=1$ iff $X_i \in [l,u]$
- $\sum A_{ilu} \leq u-l+1$

Can be given directly to MIP solver

Easily encoded into SAT

AllDifferent constraint

- ⇒ Simple decomposition
 - $A_{ilu}=1$ iff $X_i \in [l,u]$
 - $\sum A_{ilu} \leq u-l+1$
- ⇒ Does not hinder propagation
 - Domain consistency on decomposition achieves range consistency on AllDifferent

AllDifferent constraint

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 - Time complexity $O(nd^3)$ down branch

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AllDifferent constraint

⇒ Simple decomposition

- $A_{i|u}=1$ iff $X_i \in [l,u]$
- $\sum A_{i|u} \leq u-l+1$

⇒ Does not hinder propagation

- Unit propagation on SAT encoding achieves range consistency on AllDifferent

Other decompositions

- ⇒ Similar interval based decompositions for many other global constraints:
 - NValues
 - GCC
 - Common
 - Used
 - ...

That shows what we can do in
SAT ...

Now for what we cannot do in
SAT

Main result

Polynomial size CNF
decomposition of
constraint propagator

iff

Polynomial size monotone
circuit

Proof outline

Constraint propagator



Constraint checker

CNF Decomposition



Monotone circuit

All reductions polynomial

Constraint propagator

- ⇒ Function $f:P(D)\Rightarrow P(D)$
 - Monotone
 - I.e. smaller input, smaller output
 - Contracting
 - I.e. output \subseteq input
 - Idempotent
 - I.e. $f(f(\text{input})) = f(\text{input})$
 - Correct
 - Only prunes values that have no support
 - When domain wipes out, there is no support

Constraint checker

⇒ Function $f:P(D)\Rightarrow\{0,1\}$

- Monotone
 - I.e. smaller input, smaller output
- Correct
 - I.e. if $f(\text{input})=0$ then there is no support

Polynomial time constraint
propagator

iff

Polynomial time constraint
checker

CNF decomposition of constraint checker

- ⇒ Input vars of CNF encode characteristic function of $D(X)$
 - Can also have auxiliary vars
- ⇒ One output var
 - Set to false by unit propagation iff constraint checker returns 0

Monotone circuits

- ⇒ DAG of ANDs and ORs
- ⇒ Computes exactly the monotone Boolean functions
 - Note: our result has nothing to say about $P=NP$. There are, for instance, poly time monotone Boolean functions which require superpoly size monotone circuit

Main result

Polynomial size CNF decomposition
of constraint propagator/checker

iff

Polynomial size monotone circuit

Circuit complexity

- ⇒ We can now use lower bounds on monotone circuits
 - E.g. Domain consistency propagator for AllDifferent computes perfect matching in bipartite value graph
 - Smallest monotone circuit to compute such a matching is super-polynomial

Circuit complexity

- ⇒ We can now use lower bounds on monotone circuits
 - Thus, we conclude that the smallest CNF encoding of a domain consistency propagator for AllDifferent is super-polynomial in size

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- ⇒ We can now use lower bounds on monotone circuits
- Thus, we conclude that the smallest CNF encoding of a domain consistency propagator for AllDifferent is super-polynomial in size

Unfortunately there aren't too many monotone circuit complexity results to exploit

Possible (but unlikely) escapes



- Don't represent domains explicitly but just bounds
 - Exponentially more compact
- Use monotone arithmetic circuits

Conclusions

- ⇒ What we can do in SAT
 - *Some* global constraints
 - E.g. Domain consistency on REGULAR, and range/bound consistency on AllDifferent

- ⇒ What we cannot do in SAT
 - *All* global constraints
 - E.g. Domain consistency on AllDifferent